L Number	Hits	Search Text	DB	Time stamp
-	57	((steven with schulz) or (nitinkumar with patel) or (james with	USPAT;	2004/08/27 15:16
		nagashima) or (seung with ki with sul) or (bon with ho with	US-PGPUB;	
		bae)).in.	EPO; JPO	
-	17	(((steven with schulz) or (nitinkumar with patel) or (james with	USPAT;	2004/08/27 15:17
		nagashima) or (seung with ki with sul) or (bon with ho with	US-PGPUB;	
	40	bae)).in.) and ((low or high) with speed)	EPO; JPO	2004/00/27 45 20
-	10	((((steven with schulz) or (nitinkumar with patel) or (james	USPAT;	2004/08/27 15:20
		with nagashima) or (seung with ki with sul) or (bon with ho with bae)).in.) and ((low or high) with speed)) and (stator with	US-PGPUB;	
		current) and (flux with position)	EPO; JPO	
_	144	(motor with control\$4) and (((low or zero) and high) adj	USPAT;	2004/08/31 12:42
	***	speed) and (stator with current) and (flux with position)	US-PGPUB;	200 1700/31 12.12
		special and (successfully and (nax was position)	EPO; JPO	
_	17	((motor with control\$4) and (((low or zero) and high) adj	USPAT;	2004/08/31 13:23
		speed) and (stator with current) and (flux with position)) and	US-PGPUB;	200 1,00,01 10120
		((high adj speed) same (flux with position))	EPO; JPO	
-	37	(motor with control\$4) and ((low adj speed) with (rotor near2	USPAT;	2004/08/31 14:08
		position)) and ((high adj speed) with (rotor near2 position))	US-PGPUB;	,,
			EPO; JPO	
-	32	((motor with control\$4) and ((low adj speed) with (rotor near2	USPAT;	2004/08/31 13:25
		position)) and ((high adj speed) with (rotor near2 position)))	US-PGPUB;	
		not (((motor with control\$4) and (((low or zero) and high) adj	EPO; JPO	
		speed) and (stator with current) and (flux with position)) and		
		((high adj speed) same (flux with position))) not ((motor with		
		control\$4) and (((low or zero) and high) adj speed) and (stator		
		with current) and (flux with position))		
-	32	(((motor with control\$4) and ((low adj speed) with (rotor near2	USPAT;	2004/08/31 13:26
		position)) and ((high adj speed) with (rotor near2 position)))	US-PGPUB;	
		not (((motor with control\$4) and (((low or zero) and high) adj	EPO; JPO	
		speed) and (stator with current) and (flux with position)) and		
		((high adj speed) same (flux with position))) not ((motor with		
		control\$4) and (((low or zero) and high) adj speed) and (stator with current) and (flux with position))) not (318/\$.ccls. and		
		(((low or zero) and high) adj speed) and (stator with current)		
		and (flux with position))		
_	38	((low adj speed) and (high adj speed) and (rotor near2	USPAT;	2004/08/31 14:44
	30	position)).ab.	US-PGPUB;	200 1/00/31 14.44
		, position, y, as i	EPO; JPO	
-	31	(((low adj speed) and (high adj speed) and (rotor near2	USPAT;	2004/08/31 14:23
	-	position)).ab.) not ((((motor with control\$4) and ((low adj	US-PGPUB;	2001,00,0111125
		speed) with (rotor near2 position)) and ((high adj speed) with	EPO; JPO	,
		(rotor near2 position))) not (((motor with control\$4) and (((low	, , , ,	
		or zero) and high) adj speed) and (stator with current) and		
		(flux with position)) and ((high adj speed) same (flux with		
		position))) not ((motor with control\$4) and (((low or zero) and		
		high) adj speed) and (stator with current) and (flux with		
		position))) not (318/\$.ccls. and (((low or zero) and high) adj		
		speed) and (stator with current) and (flux with position)))		
-	0	gopinath adj observer	USPAT;	2004/08/31 14:33
			US-PGPUB;	
	270		EPO; JPO	
-	370	gopinath	USPAT;	2004/08/31 14:24
			US-PGPUB;	
-	44	goninath and motor and control®4	EPO; JPO	2004/00/24 44:05
	44	gopinath and motor and control\$4	USPAT;	2004/08/31 14:25
			US-PGPUB;	
_	24	gopinath with observer	EPO; JPO	2004/00/21 14:40
	47	Sobulati Miti Observei	USPAT; US-PGPUB;	2004/08/31 14:40
	•		EPO; JPO	
-	2	(gopinath with observer) not (gopinath and motor and	USPAT;	2004/08/31 14:34
	~	control\$4)	US-PGPUB;	2007/00/31 14.34
			. JJ rurub.	